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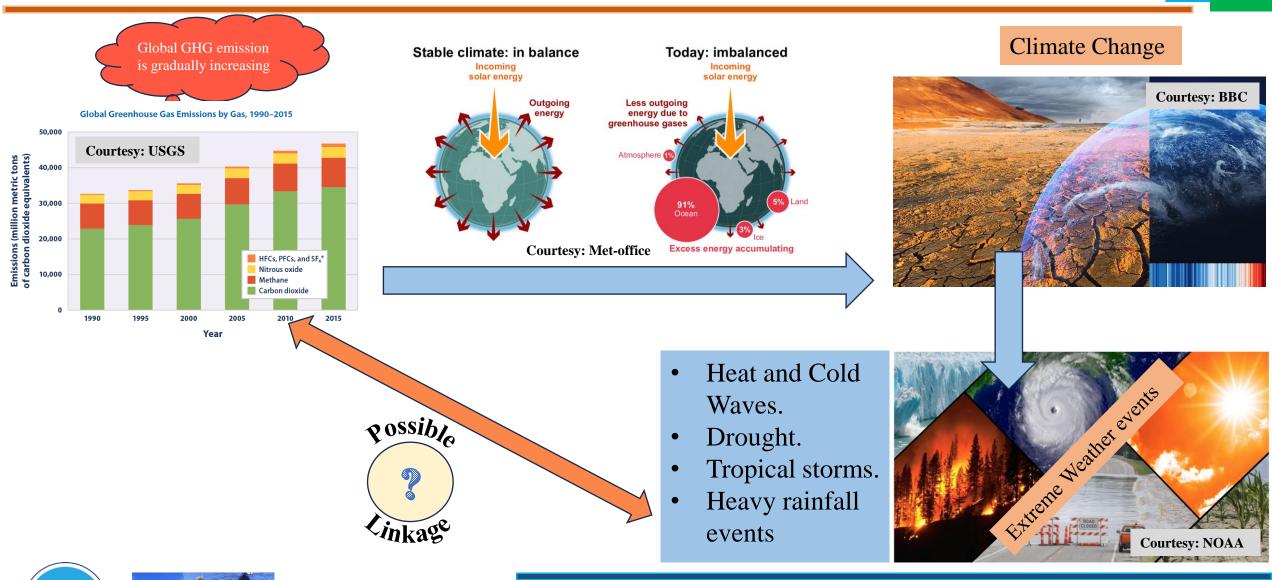
CO₂ surface flux estimation using ensemble based Kalman Filter approach



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Introduction



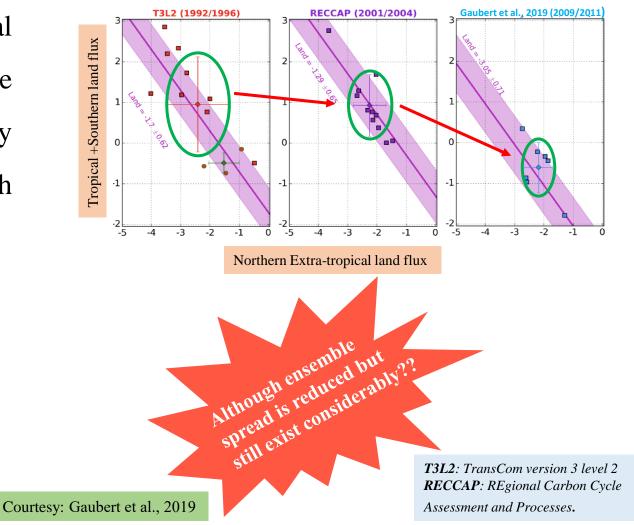
Background

 CO_2 is the primary GHG having largest global warming potential (= 1, used as reference). Accurate quantification of CO_2 sink/source is extremely significant in understanding global commitment such as global stock take and the global carbon budget.

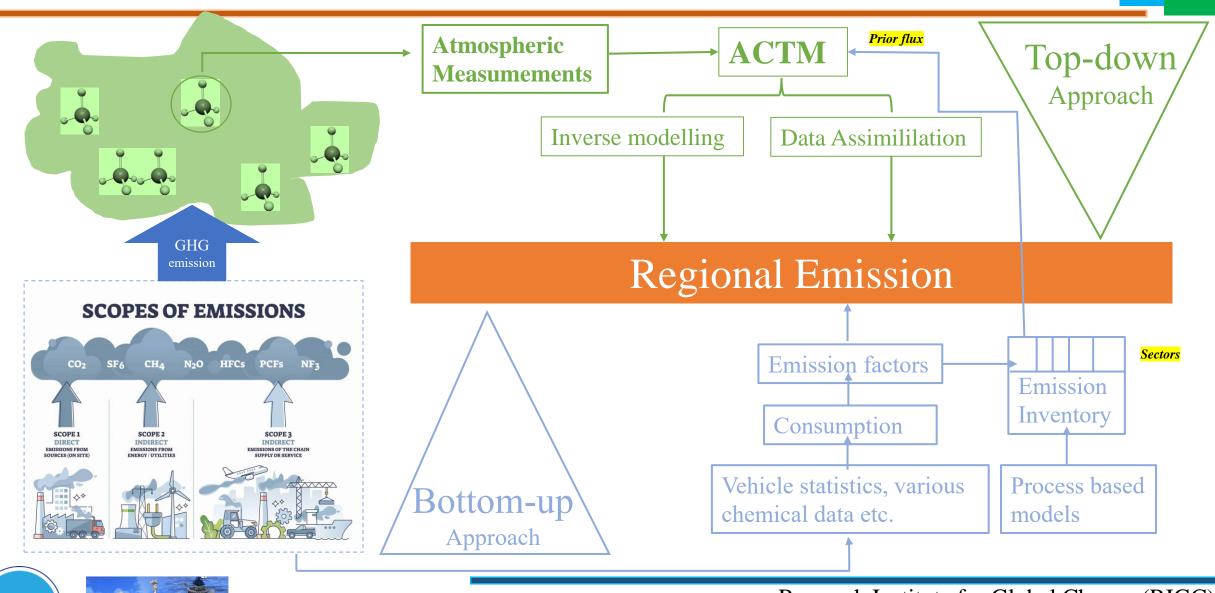
It remains a challenging task mainly due to:

- Spatio-temporal heterogeneity
- Measurement limitations
- Transport uncertainties

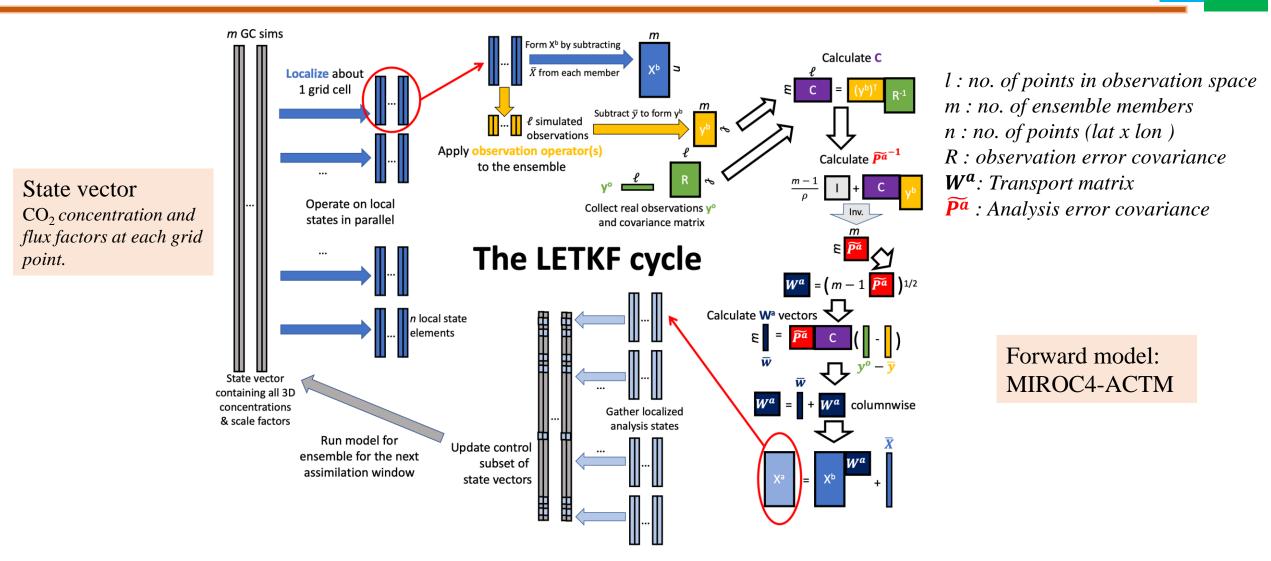




Background: Bottom-up vs. Top-down approach



Local Ensemble Transform Kalman Filter (LETKF)





MIROC4-LETKF OSSE Setup

OSSE : Observing System Simulation Experiment

First step for the implementation and testing of a DA system. It is useful to investigate the skill of the DA system using synthetic observation data before applying it to a real world problem.

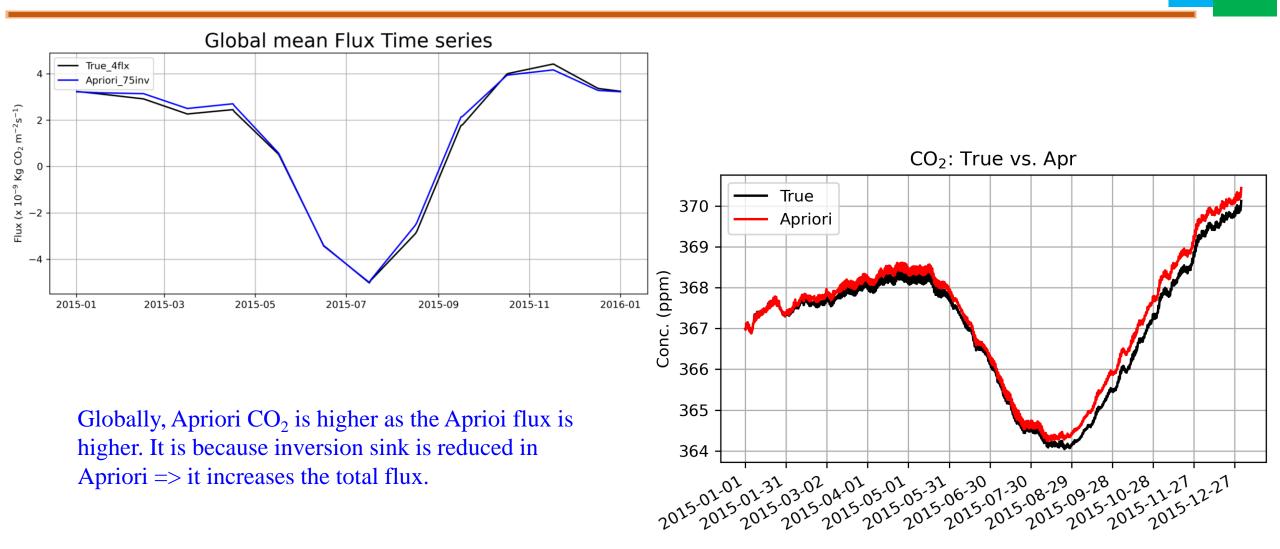
To start an OSSE experiment using MIROC4-LETKF system, we need the following:

- Synthetic observation data and its associated uncertainty.
- *Prior flux and associated uncertainty.*
- Initial CO₂ values.

In our experiment: Experiment year : 2015 No. of ensembles : 100 True flux: Fossil fuel (GridFED; Jones et al., 2021) + Landbiosphere (CASA monthly; Randerson et al., 1997) + Ocean (Takahashi et al., 2009) + Inversion flux (Chandra et al., 2022). Apriori flux: Fossil fuel + Land-biosphere + Ocean + 75% Inversion flux. Window length: 3 days Inflation: 10% fixed multiplicative Gross error: 10 Horizontal correlation length = 2000 km Vertical correlation length = 0.3 ln hPa

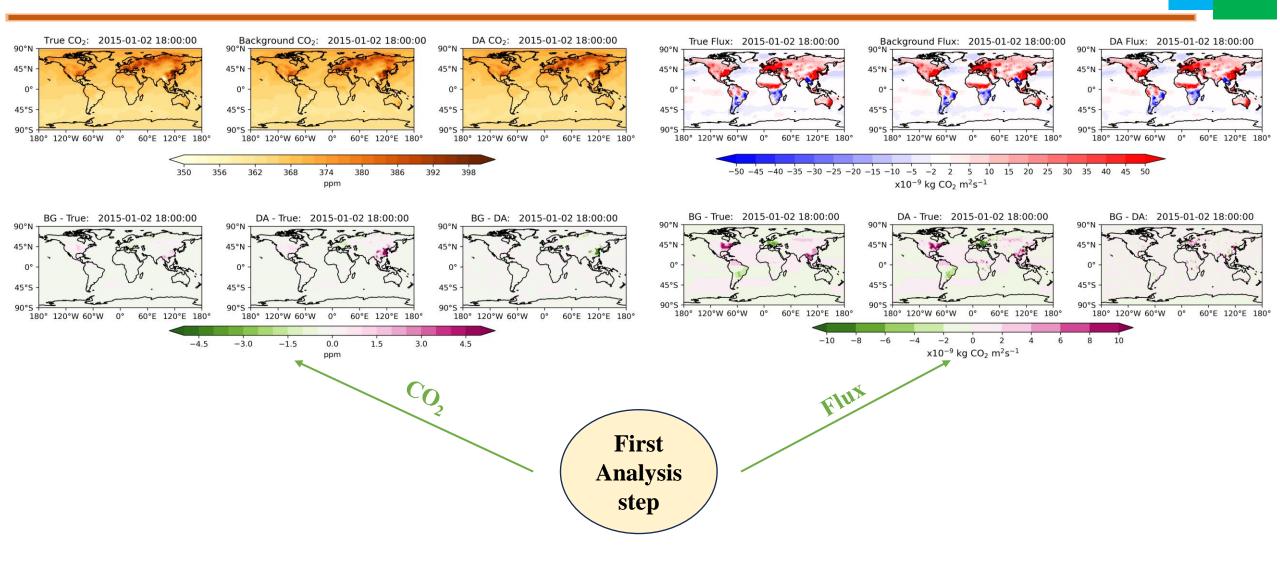


MIROC4-LETKF OSSE: Synthetic True vs. Apriori



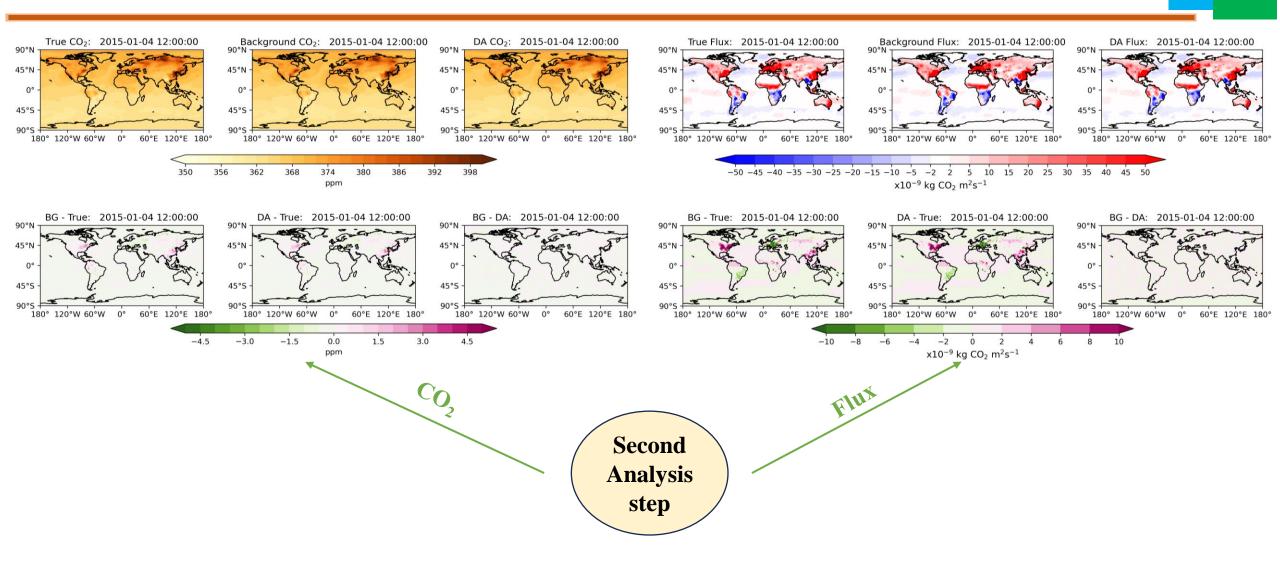
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Results: Spatial distribution of analysed CO₂ and flux



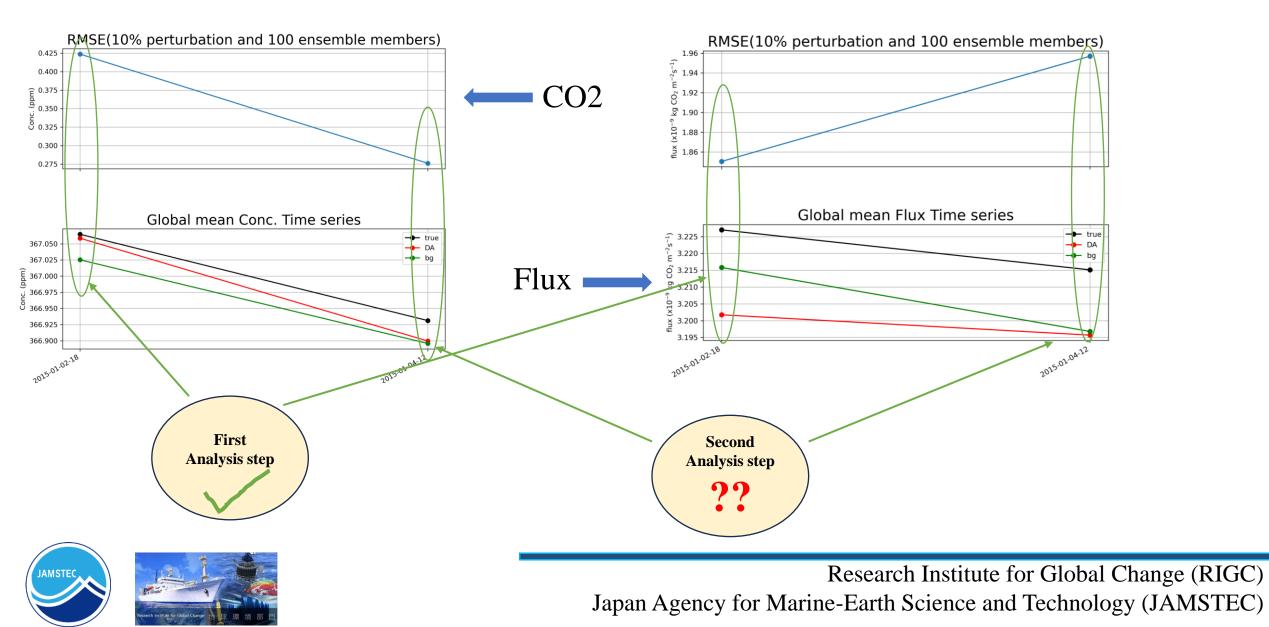


Results: Spatial distribution of analysed CO₂ and flux





Results: Global RMSE of analysed CO₂ and flux



Possible solution of this problem:

- □ It is observed that LETKF is extremely sensitive to the prior flux and its uncertainty.
- **Observation error is also an important factor for the convergence. Realistic error might help the system to converge.**
- □ Theoretically, background error covariance is getting underdispersed over time. Therefore, we need to inflate it. This will help the LETKF system to maintain the background/prior flux uncertainty. There are various covariance inflation
 - technique. One of such procudure is RTPS (relaxation-to-prior spread). In this method, we force the system to maintain
 - a predefined (provided by the user) percentage of prior flux uncertainty for the following timesteps.

□ *More test simulation and diagnostics are needed.*



In this study, LETKF is tested for the optimization CO_2 flux and concentration. As of now,

- Technical implementation and testing of LETKF is finished and the system (MIROC4-LETKF) is working well.
- As observed earlier, CO₂ and flux are not optimized correctly from the second analysis window onwards due to inaccurate prior flux and its uncertainty as well as implementation of correct covariance inflation technique.



Thank you

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